

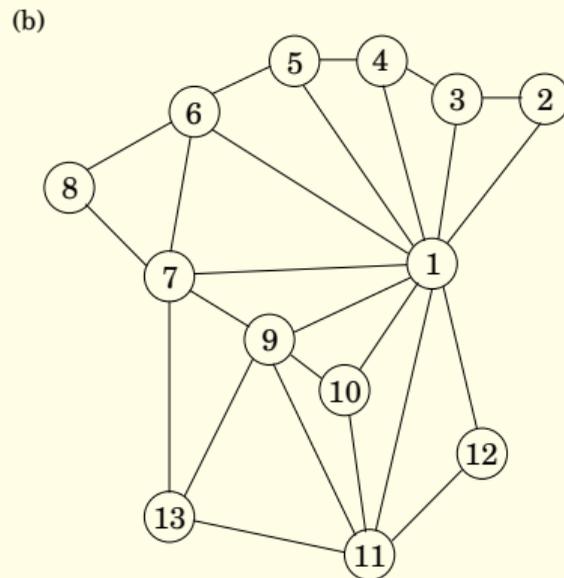
# CSE 548: Algorithms

## Basic Graph Algorithms

R. Sekar

# Overview

- Graphs provide a concise representation of a range of problems
  - Map coloring** – more generally, resource contention problems
  - Networks** – communication, traffic, social, biological, ...



# Definition and Representations

## Definition

- A *graph*  $G = (V, E)$ , where  $V$  is a set of vertices, and  $E$  a set of edges.
- An edge  $e$  of the form  $(v_1, v_2)$  is said to span vertices  $v_1$  and  $v_2$ .
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## Adjacency matrix

A graph  $(V = \{v_1, \dots, v_n\}, E)$  can be represented by an  $n \times n$  matrix  $a$ , where  $a_{ij} = 1$  iff  $(v_i, v_j) \in E$

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Each vertex  $v$  is associated with a linked list consisting of all vertices  $u$  such that  $(v, u) \in E$ .

Adjacency matrix uses  $O(n^2)$  storage; adjacency list uses  $O(|V| + |E|)$  storage.

# Depth-First Search (DFS)

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dfs(V, E)
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  if not visited[v] then explore(V, E, v)
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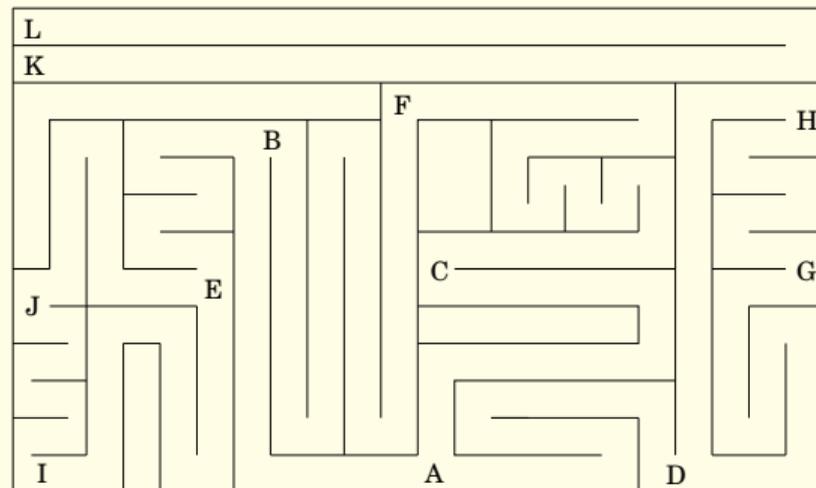
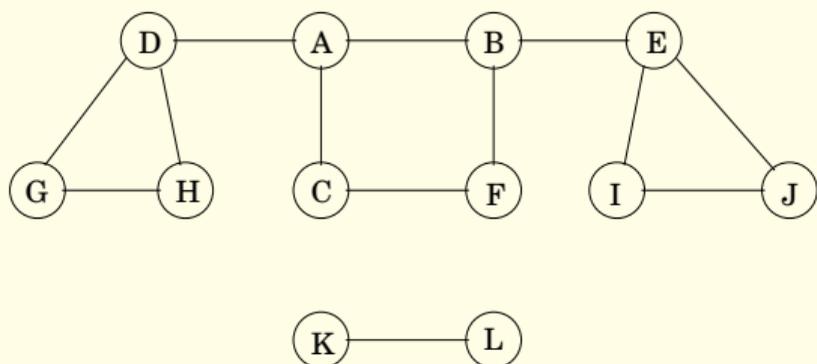
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*explore*( $V, E, v$ )

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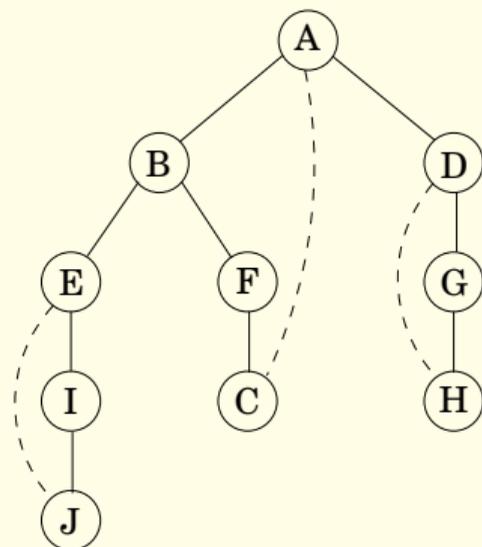
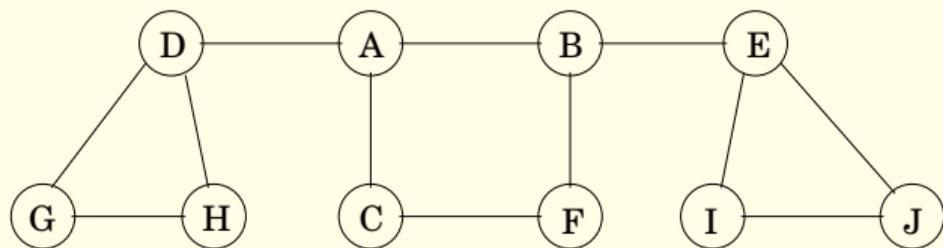
visited[ $v$ ] = true
previsit( $v$ )      /*A placeholder for now*/
foreach  $(v, u) \in E$  do
  if not visited[ $u$ ] then explore( $V, E, u$ )
postvisit( $v$ )    /*Another placeholder*/
  
```

# Graphs, Mazes and DFS



If a maze is represented as a graph, then DFS of the graph amounts to an exploration and mapping of the maze.

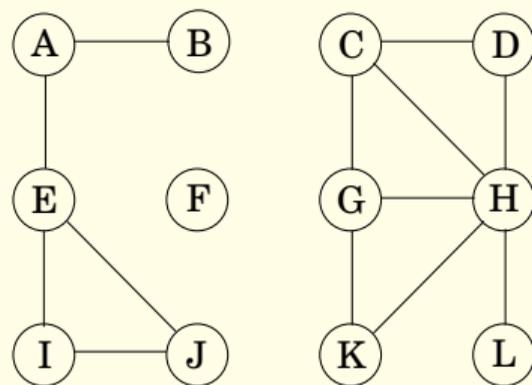
# A graph and its DFS tree



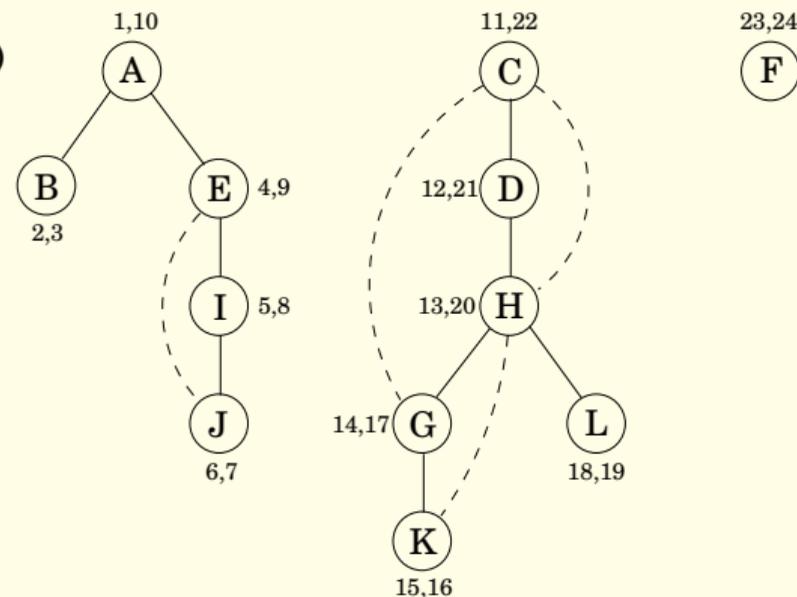
DFS uses  $O(|V|)$  space and  $O(|E| + |V|)$  time.

# DFS and Connected Components

(a)



(b)



A *connected component* of a graph is a maximal subgraph where there is path between any two vertices in the subgraph, i.e., it is a maximal *connected subgraph*.

# DFS Numbering

Associate post and pre numbers with each visited node by defining *previsit* and *postvisit*

*previsit*(*v*)

$pre[v] = clock$

$clock++$

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*previsit*( $v$ )

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*postvisit*( $v$ )

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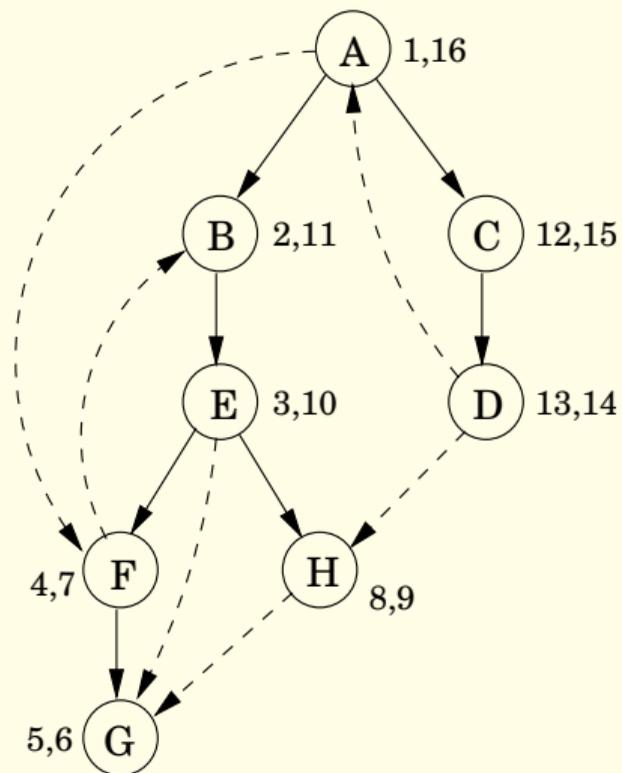
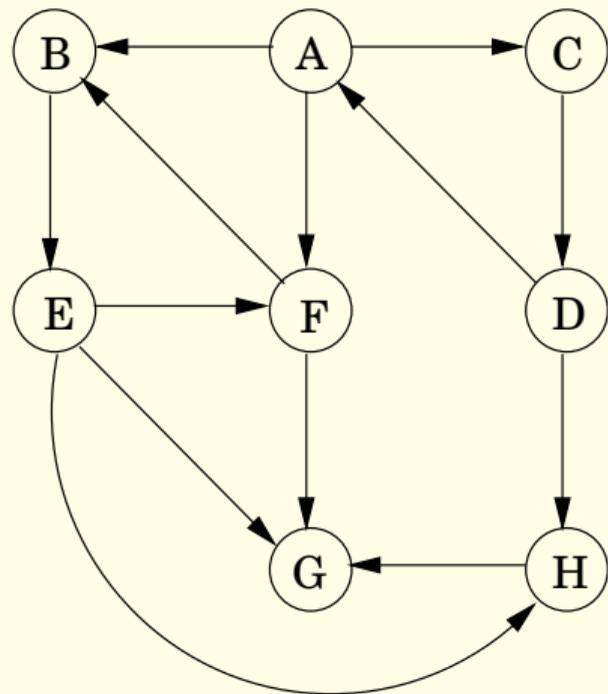
$post[v] = clock$

$clock++$

## Property

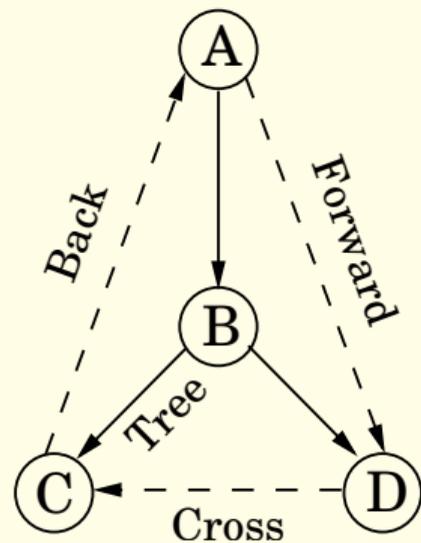
For any two vertices  $u$  and  $v$ , the intervals  $[pre[u], post[u]]$  and  $[pre[v], post[v]]$  are either disjoint, or one is contained entirely within another.

# DFS of Directed Graph



# DFS and Edge Types

## DFS tree



pre/post ordering for $(u, v)$				Edge type
[	[	]	]	Tree/forward
$u$	$v$	$v$	$u$	
[	[	]	]	Back
$v$	$u$	$u$	$v$	
[	]	[	]	Cross
$v$	$v$	$u$	$u$	

*No cross edges in undirected graphs!*

Back and forward edges merge

# Directed Acyclic Graphs (DAGs)

A directed graph that contains no cycles.

Often used to represent (acyclic) dependencies, partial orders,...

## Property (DAGs and DFS)

- *A directed graph has a cycle iff its DFS reveals a back edge.*
- *In a dag, every edge leads to a vertex with lower post number.*
- *Every dag has at least one source and one sink.*

# Topological Sort

A way to linearize DAGs while ensuring that for every vertex, all its ancestors appear before itself.

**Applications:** spreadsheet recomputation of formulas, Make (and other compile/build systems) and Task scheduling/project management.

# Topological Sort

*topoSort*( $V, E$ )

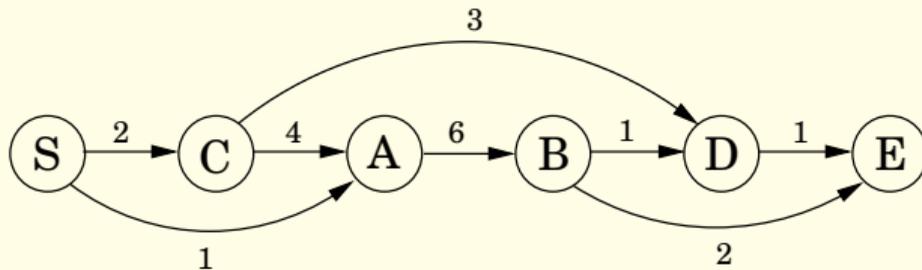
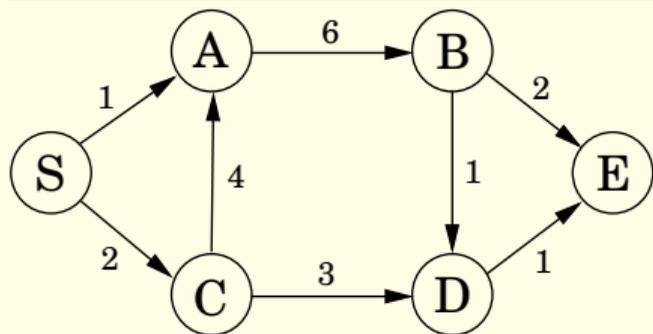
**while**  $|V| \neq 0$

**if** there is a vertex  $v$  in  $V$  with in-degree of 0

**output**  $v$

$V = V - \{v\}; E = E - \{e \in E \mid e \text{ is incident on } v\}$

**else output** “graph is cyclic”; **break**



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**Correctness:**

- If there is no vertex with in-degree 0, it is not a DAG
- When the algorithm outputs  $v$ , it has already output  $v$ 's ancestors

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**Performance:** What is the runtime? Can it be improved using DFS properties of DAGs?

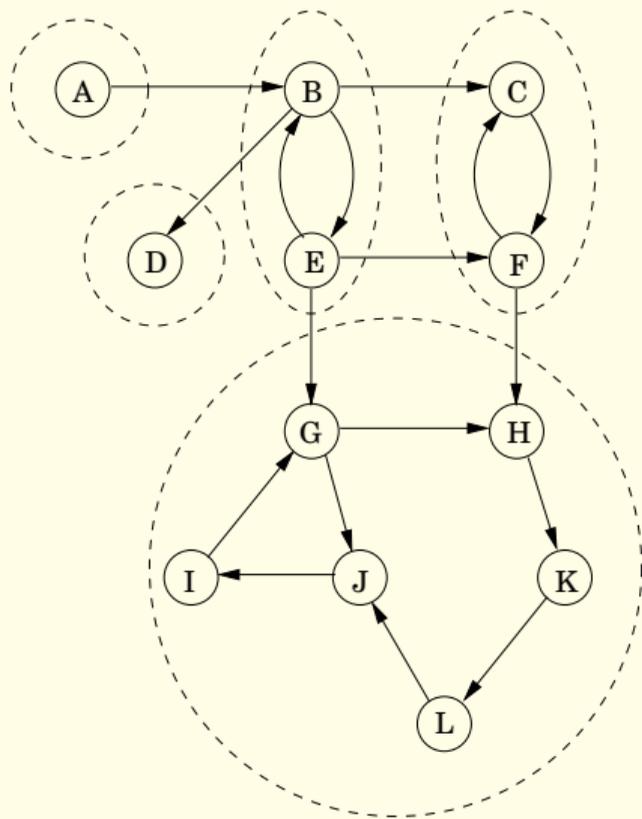
# Strongly Connected Components (SCC)

For directed graphs, SCCs are the equivalent of connected components in undirected graphs.

## Definition (SCC)

- Two vertices  $u$  and  $v$  in a directed graph are **connected** if there is a path from  $u$  to  $v$  and vice-versa.
- A directed graph is **strongly connected** if any pair of vertices in the graph are connected.
- A **subgraph** of a directed graph is said to be an SCC if it is a **maximal subgraph** that is strongly connected.

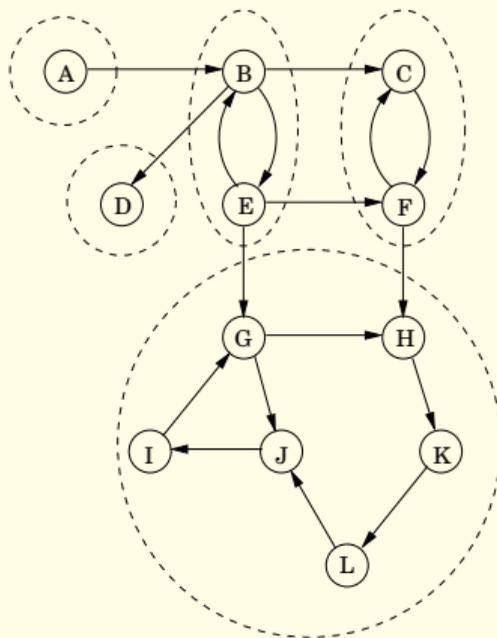
# SCC Example



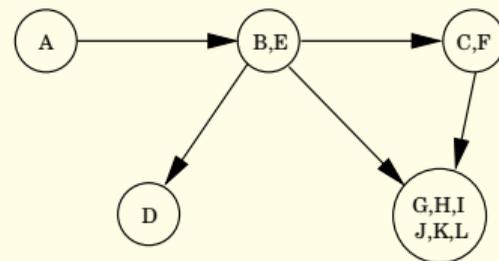
# DAG of SCCs

## Property

*Every directed graph is a dag of its strongly connected components.*



(b)



# Towards an Algorithm for Computing SCCs

- Pick a sink SCC.
- Output all nodes in this SCC.
  - We can just do a DFS starting from any node  $v$  in this SCC!
    - Because this is a sink SCC, this DFS cannot reach any other SCC, so will only output this SCC.
- Delete these nodes from the graph and repeat the whole process.

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But how do we find a node in the sink SCC?

# Towards an Algorithm for Computing SCCs

## Property

- *When  $\text{explore}(u)$  returns, it has visited all (and only) the nodes reachable from  $u$ .*
- *If  $C$  and  $C'$  are SCCs and there is an edge from  $C$  to  $C'$  then:  
the highest post number in  $C$  will be larger than the highest post number in  $C'$ .*

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## Property

*For a graph  $G$ , let  $G_R$  denote the graph formed by reversing every edge in  $G$ . Then*

- *The SCCs of  $G$  and  $G_R$  are identical.*
- *A source SCC of  $G_R$  is a sink SCC of  $G$ .*

# An Algorithm for Computing SCCs

1. Construct  $G_R$  from  $G$  by reversing every edge in the given graph  $G$ .
2. The node  $v$  with the highest post number is in a source SCC of  $G_R$ .
  - So,  $v$  must be in a sink SCC of  $G$ .
3. Invoke  $explore(v)$  in  $G$  to output this sink SCC.
4. Delete these nodes from  $G$  and  $G_R$ , and repeat from Step 2.

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Can we do all this in linear time?

# Breadth-first Search (BFS)

- Traverse the graph by “levels”
  - $BFS(v)$  visits  $v$  first
  - Then it visits all immediate children of  $v$
  - then it visits children of children of  $v$ , and so on.

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- As compared to DFS, BFS uses a queue (rather than a stack) to remember vertices that still need to be explored

# BFS Algorithm

*bfs*( $V, E, s$ )

**foreach**  $u \in V$  **do**  $visited[u] = false$

$q = \{s\}; visited[s] = true$

**while**  $q$  is nonempty **do**

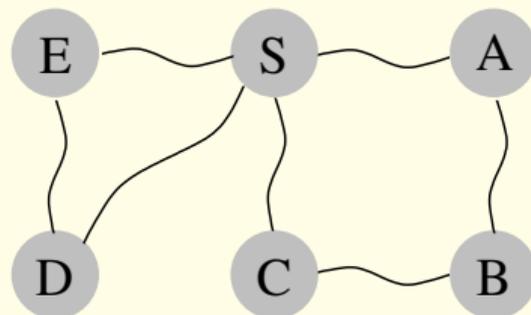
$u = deque(q)$

**foreach** edge  $(u, v) \in E$  **do**

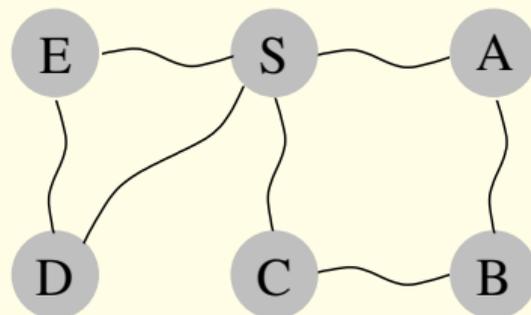
**if not**  $visited[v]$  **then**

$queue(q, v); visited[v] = true$

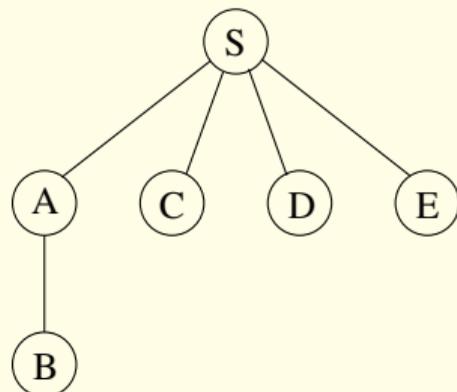
# BFS Algorithm Illustration



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Order of visitation	Queue contents after processing node
	[S]
S	[A C D E]
A	[C D E B]
C	[D E B]
D	[E B]
E	[B]
B	[]



# Shortest Paths and BFS

BFS automatically computes shortest paths!

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**foreach**  $u \in V$  **do**  $dist[u] = \infty$

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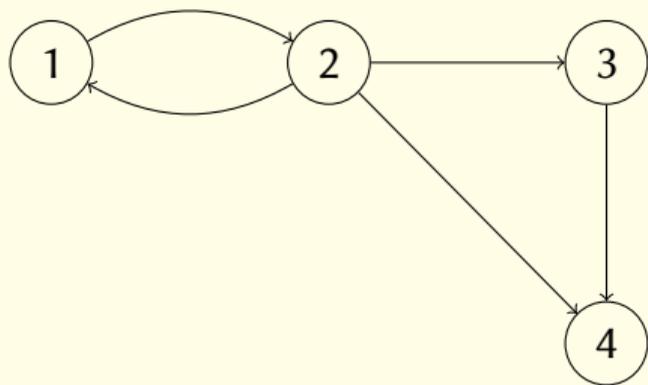
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```

But not all paths are created equal! We would like to compute shortest weighted path — a topic of future lecture.

# Graph paths and Boolean Matrices

A graph and its boolean matrix representation



$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

# Graph paths and Boolean Matrices

- Let  $A$  be the adjacency matrix for a graph  $G$ , and  $B = A \times A$ . Now,  $B_{ij} = 1$  iff there is path in the graph of length 2 from  $v_i$  to  $v_j$

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- Let  $C = A + B$ . Then  $C_{ij} = 1$  iff there is path of length  $\leq 2$  between  $v_i$  and  $v_j$

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- Let  $C = A + B$ . Then  $C_{ij} = 1$  iff there is path of length  $\leq 2$  between  $v_i$  and  $v_j$
- Define  $A^* = A^0 + A^1 + A^2 + \dots$ . If  $D = A^*$  then  $D_{ij} = 1$  iff  $v_j$  is reachable from  $v_i$ .

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$A^2 = \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$A^3 = \begin{bmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

# Shortest paths and Matrix Operations

- Redefine operations on matrix elements so that  $+$  becomes *min*, and  $*$  becomes integer addition.

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- $D = A^*$  then  $D_{ij} = k$  iff the shortest path from  $v_j$  to  $v_i$  is of length  $k$